

Parameter Identification in Piezoelectricity

DFG Junior Research Group

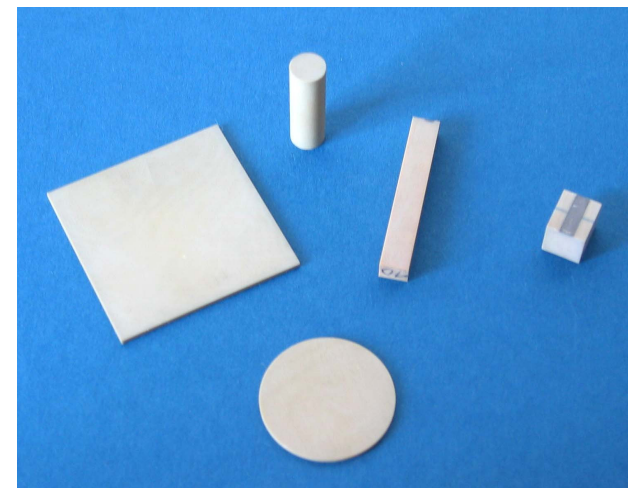
Inverse Problems in Piezoelectricity

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Research: Inverse Problems

- Piezoelectric equations

$$\rho \frac{\partial^2 \vec{u}}{\partial t^2} - \text{DIV} \left(\mathbf{c}^E \text{DIV}^T \vec{u} + \mathbf{e}^T \text{grad} \phi \right) = 0 \in \Omega$$

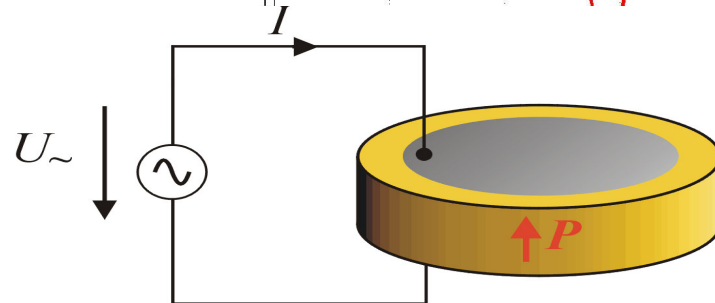
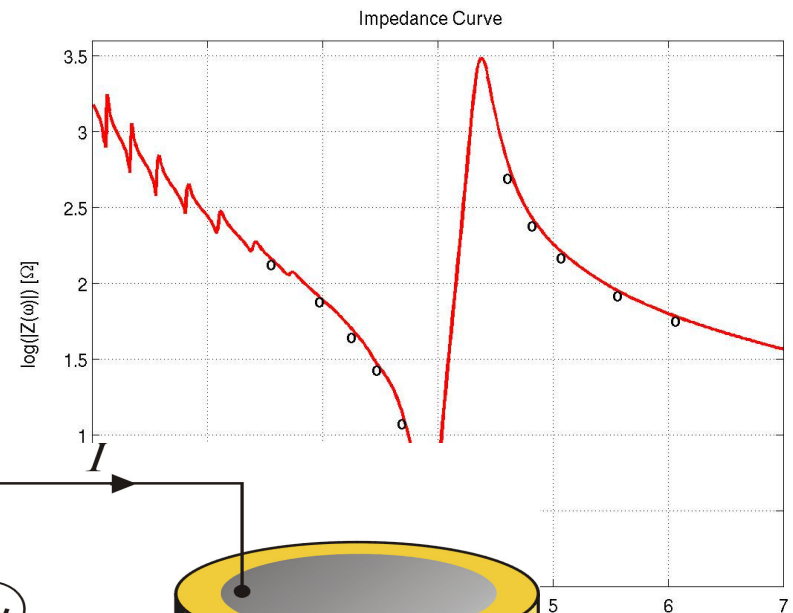
$$-\text{div} \left(\mathbf{e} \text{DIV}^T \vec{u} - \epsilon^S \text{grad} \phi \right) = 0 \in \Omega$$

- Discretization by FEM
- Inverse Problem

$$\hat{\mathbf{F}} : X^{par} \rightarrow Y^{meas}$$

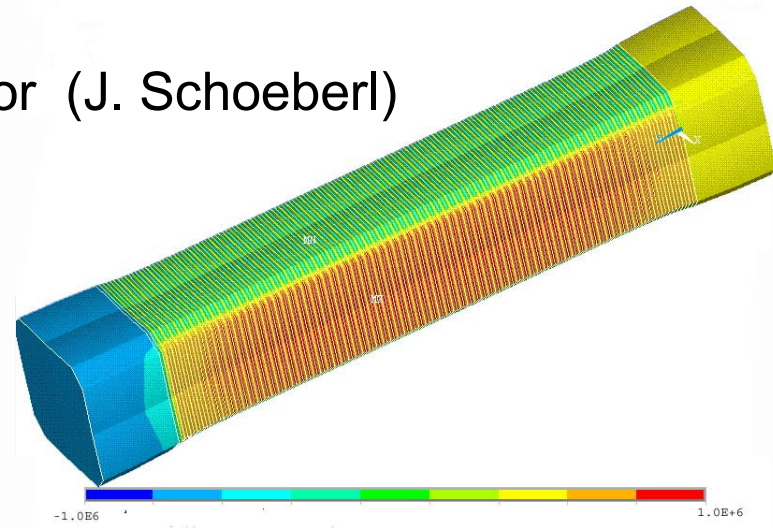
$$\hat{\mathbf{F}}(\mathbf{c}^E, \mathbf{e}, \epsilon^S) = \tilde{q}_{meas}^e$$

- Multilevel methods for nonlinear problems



Open Tasks – Discussions at RICAM

- Homogenization for stack actuator (J. Schoeberl)
- Optimal experiment design (V. Schulz)



- Nonlinear piezoelectric equations:

$$c^E = c^E(|\mathcal{B}\vec{d}|)$$

$$e = e(|\mathcal{B}\vec{d}|, |\text{grad}\phi|)$$

$$\varepsilon^S = \varepsilon^S(|\text{grad}\phi|)$$

- Identifiability results -> (G. Nakamura)
- Adaptivity -> (B. Vexler, H. Egger)



Any Questions ?



Department of Sensor Technology

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Piezoelectric PDEs (transient)

$$\rho \frac{\partial^2 \vec{u}}{\partial t^2} - \text{DIV} \left(c^E \text{DIV}^T \vec{u} + e^T \text{grad} \phi \right) = 0 \in \Omega$$

$$- \text{div} \left(e \text{DIV}^T \vec{u} - \varepsilon^S \text{grad} \phi \right) = 0 \in \Omega$$

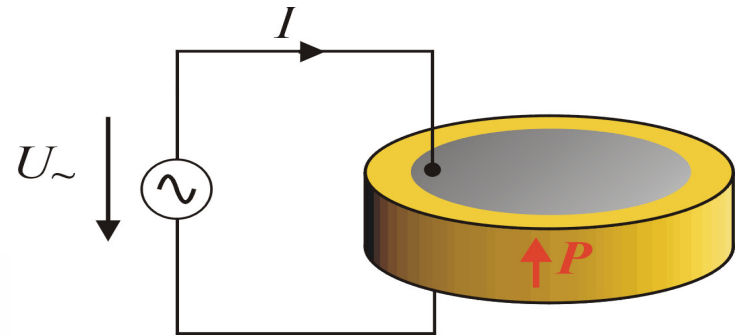
Boundary conditions:

$$N^T \sigma = 0 \quad \text{on } \partial\Omega$$

$$\phi = 0 \quad \text{on } \Gamma_g \dots \text{grounded electrode}$$

$$\phi = \phi^e \quad \text{on } \Gamma_e \dots \text{loaded electrode}$$

$$\vec{D} \cdot \vec{N} = 0 \quad \text{on } \partial\Omega \setminus (\Gamma_g \cup \Gamma_e)$$



Piezoelectric Material Law

(6 mm crystal class)

$$\begin{pmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \sigma_4 \\ \sigma_5 \\ \sigma_6 \\ D_1 \\ D_2 \\ D_3 \end{pmatrix} = \begin{pmatrix} c_{11}^E & c_{12}^E & c_{13}^E & \cdot & \cdot & \cdot & \cdot & \cdot & -e_{13} \\ c_{12}^E & c_{11}^E & c_{13}^E & \cdot & \cdot & \cdot & \cdot & \cdot & -e_{13} \\ c_{13}^E & c_{13}^E & c_{33}^E & \cdot & \cdot & \cdot & \cdot & \cdot & -e_{33} \\ \cdot & \cdot & \cdot & c_{44}^E & \cdot & \cdot & \cdot & -e_{15} & \cdot \\ \cdot & \cdot & \cdot & \cdot & c_{44}^E & \cdot & -e_{15} & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & c_{66}^E & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & e_{15} & \cdot & \epsilon_{11}^S & \cdot & \cdot \\ \cdot & \cdot & \cdot & e_{15} & \cdot & \cdot & \cdot & \epsilon_{11}^S & \cdot \\ e_{13} & e_{13} & e_{33} & \cdot & \cdot & \cdot & \cdot & \cdot & \epsilon_{33}^S \end{pmatrix} \begin{pmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \\ S_6 \\ E_1 \\ E_2 \\ E_3 \end{pmatrix}$$

where $c_{66}^E = \frac{1}{2}(c_{11}^E + c_{12}^E)$

elasticity [N/m²],

piezoelectric coupling [(C/m²)],

permittivity [F/m]

Piezoelectric Effect

$$\vec{\sigma} = \mathbf{c}^E \vec{S} - \mathbf{e}^T \vec{E}$$

$$\vec{D} = \mathbf{e} \vec{S} + \epsilon^S \vec{E}$$

$\vec{\sigma}$... mechanical stress

$\vec{S} = \text{DIV} \vec{u}$... mechanical strain

$\vec{E} = -\text{grad} \phi$... electric field

\vec{D} ... dielectric displacement

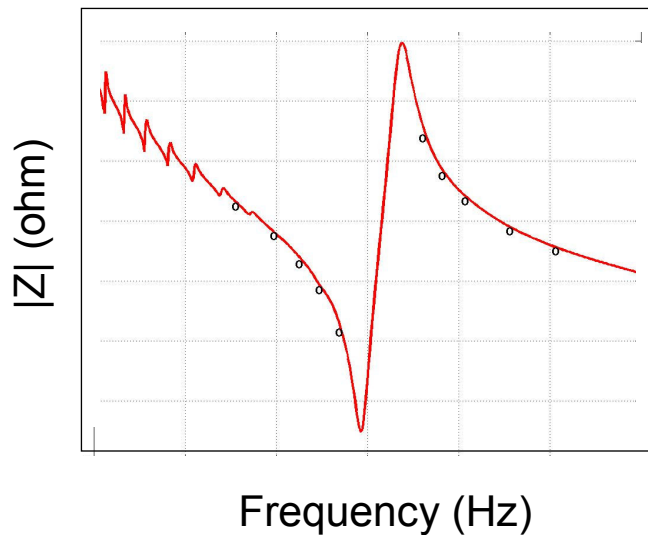
\vec{u} ... mechanical displacement

ϕ ... electric potential

+ Newton's law: $\nabla \cdot \vec{\sigma} = \rho \frac{\partial^2 \vec{u}}{\partial t^2}$

+ Gauss' law: $\nabla \cdot \vec{D} = 0$

Inverse Problem – Identification by Simulation of Piezoelectric PDEs



Find material tensors \mathbf{c}^E , \mathbf{e} , ϵ^S from impedance measurements for different frequencies ω

$$Z(\omega) = \frac{\hat{\phi}^e(\omega)}{j\omega \hat{q}^e(\omega)}$$

$$\hat{q}^e = \int_{\Gamma_e} \vec{n} \left(\mathbf{e} \text{DIV}^T \vec{u} - \epsilon^S \text{grad} \hat{\phi} \right) d\Gamma_e$$

Z –impedance, ϕ^e –impressed voltage, \hat{q}^e –surface charge

- Nonlinear operator equation $\hat{\mathbf{F}}(\mathbf{c}^E, \mathbf{e}, \epsilon^S) = \hat{q}_{meas}^e$
- Forward operator $\hat{\mathbf{F}}$ involves set of PDE solution

Inverse Problem – Solution/ Regularization by Inexact Newton Methods

```
Choose  $\mathbf{p}^0 = (\mathbf{c}^E, \mathbf{e}, \varepsilon^S)^0$ ;  
set  $k = 0$ ;  
while  $\|\hat{\mathbf{y}} - \hat{\mathbf{F}}(p^k)\| \geq \tau\delta$  do  
  set  $s_0^k = 0$ ;  
  while  $\|\hat{\mathbf{y}} - \hat{\mathbf{F}}(p^k) - \hat{\mathbf{F}}'(p^k)[s_n^k]\| \geq \eta_k \|\hat{\mathbf{y}} - \hat{\mathbf{F}}(p^k)\|$  do  
     $s_n^k = \Phi(\hat{\mathbf{F}}'(p^k), \hat{\mathbf{y}} - \hat{\mathbf{F}}(p^k), s_{n-1}^k)$ ;  
     $n++$ ;  
     $\mathbf{p}^{k+1} = \mathbf{p}^k + s_n^k$ ;  
     $k++$ ;
```

δ - data noise, $\tau > 1$, η_k - tolerance factor

Choices for $\Phi(\dots)$:

Landweber's iteration, ν -methods, CG

Numerical Results – Simultaneous Reconstruction of all parameters

