

NIPG - The Nonsymmetric Interior Penalty Galerkin Method

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The Model Problem

Restrict ourselves to the model problem

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

Ω – a convex polygonal domain

f – a given function in $L^2(\Omega)$

Rewrite the problem as a first-order system

$$\sigma = \nabla u \quad \text{in } \Omega \quad (1)$$

$$-\nabla \cdot \sigma = f \quad \text{in } \Omega \quad (2)$$

The Weak Formulation

Multiply (1)-(2) by test functions τ and v , and integrate on a subset K of Ω

$$\begin{aligned}\int_K \sigma \cdot \tau dx &= - \int_K u \nabla \cdot \tau dx + \int_{\partial K} u n_K \cdot \tau ds \\ \int_K \sigma \cdot \nabla v dx &= \int_K f v dx + \int_{\partial K} \sigma \cdot n_K v ds\end{aligned}$$

n_K – the outward normal unit vector to ∂K

This is the weak formulation we will use to define the DG methods.

The Flux Formulation

The finite element spaces associated with the triangulation $\Pi_h = \{K\}$ of Ω , $P(K) = P_p(K)$ ($p \geq 1$), $\Sigma(K) = [P_p(K)]^2$

$$V_h := \{v \in L^2(\Omega) : v|_K \in P(K) \quad \forall K \in \Pi_h\}$$

$$\Sigma_h := \{\tau \in [L^2(\Omega)]^2 : \tau|_K \in \Sigma(K) \quad \forall K \in \Pi_h\}$$

Find $u_h \in V_h$ and $\sigma \in \Sigma_h$ such that for all $K \in \Pi_h$, we have

$$\int_K \sigma_h \cdot \tau dx = - \int_K u_h \nabla \cdot \tau dx + \int_{\partial K} \hat{u}_K n_K \cdot \tau ds \quad \forall \tau \in \Sigma(K) \quad (3)$$

$$\int_K \sigma_h \cdot \nabla v dx = \int_K f v dx + \int_{\partial K} \hat{\sigma}_K \cdot n_K v ds \quad \forall v \in P(K) \quad (4)$$

Numerical fluxes $\hat{\sigma}_K$ and \hat{u}_K are approximations to $\sigma = \nabla u$ and to u on the boundary of K .

Traces and Numerical Fluxes

- The traces of functions in $H^1(\Pi_h)$ belong to $T(\Gamma) := \Pi_{K \in \Pi_h} L^2(\partial K)$, Γ , the union of the boundaries of the elements K of Π_h , functions in $T(\Gamma)$ are double-valued on $\Gamma^0 := \Gamma \setminus \partial\Omega$ and single-valued on $\partial\Omega$.
- Numerical fluxes are consistent if $\hat{u}(v) = v|_\Gamma$, $\hat{\sigma}(v, \nabla v) = \nabla v|_\Gamma$, conservative if $\hat{u}(\cdot)$ and $\hat{\sigma}(\cdot, \cdot)$ are single-valued on Γ .
- Trace operators
 - e , an interior edge shared by elements K_1 and K_2 , n_1 and n_2 , unit normal vector on e pointing exterior to K_1 and K_2 , ε_h^o the set of interior edges e , ε_h^∂ , the set of boundary edges.
 - For $q \in T(\Gamma)$, with $q_i := q|_{\partial K_i}$, $\{q\} = \frac{q_1 + q_2}{2}$, $[[q]] = q_1 n_1 + q_2 n_2$, on $e \in \varepsilon_h^o$
 - For $\varphi \in [T(\Gamma)]^2$, with $\varphi_i := \varphi|_{\partial K_i}$, $\{\varphi\} = \frac{\varphi_1 + \varphi_2}{2}$, $[[\varphi]] = \varphi_1 \cdot n_1 + \varphi_2 \cdot n_2$, on $e \in \varepsilon_h^o$
 - $[[q]] = qn$, $\{\varphi\} = \varphi$, on $e \in \varepsilon_h^\partial$

The Primal Formulation

In (3)-(4), we add over all the element, use the average $\{\}$ and jump $[[\cdot]]$ operators, express σ_h solely in terms of u_h , apply the integration by parts formula, we obtain

$$B_h(u_h, v) = \int_{\Omega} f v dx \quad \forall v \in V_h \quad (5)$$

$$\begin{aligned} B_h(u_h, v) := & \int_{\Omega} \nabla_h u_h \cdot \nabla_h v dx + \int_{\Gamma} ([[\hat{u} - u_h]] \cdot \{ \nabla_h v \} - \{ \hat{\sigma} \} \cdot [[v]]) ds \\ & + \int_{\Gamma^0} (\{ \hat{u} - u_h \} [[\nabla_h v]] - [[\hat{\sigma}]] \{ v \}) ds \end{aligned} \quad (6)$$

$$\hat{u} = \hat{u}(u_h), \hat{\sigma} = \hat{\sigma}(u_h, \sigma_h(u_h))$$

The primal form : $B_h(\cdot, \cdot) : H^2(\Pi_h) \times H^2(\Pi_h) \rightarrow R$

Equation 5 : The primal formulation of the method

The Primal Form of NIPG Method

Numerical flux of NIPG method

$$\begin{aligned}\hat{u}_K &= \{u_h\} + n_K \cdot [[u_h]] \\ \hat{\sigma}_K &= \{\nabla_h u_h\} - \alpha_j([[u_h]])\end{aligned}$$

where $\alpha_j([[u_h]]) = \eta_e h_e^{-1} [[u_h]]$

$$B_h(u, v) = (\nabla_h u, \nabla_h v) - \langle \{\nabla_h u\}, [v] \rangle + \langle [u], \{\nabla_h v\} \rangle + \alpha^j(u, v) \quad (7)$$

where

$$(a, b) = \int_{\Omega} ab dx$$

$$\langle a, b \rangle = \int_{\Gamma} ab ds$$

$$\alpha^j(u, v) = \sum_{e \in \varepsilon_h} \int_e \eta_e h_e^{-1} [u] \cdot [v] ds$$

η_e – are bounded uniformly above and below by positive constant

Consistency of NIPG Method (1)

We have consistency of numerical fluxes of NIPG method

$$\hat{u}(u) = u|_{\Gamma}, \quad \hat{\sigma}(u, \nabla(u))|_{\Gamma} = \nabla u$$

Then, use numerical fluxes,

$$\hat{u} = \{u\} + n_K \cdot \llbracket u \rrbracket, \quad \hat{\sigma} = \{\nabla_h u\} - \alpha_j(\llbracket u \rrbracket)$$

we have

$$\llbracket \hat{u} \rrbracket = 0, \quad \{\hat{u}\} = u$$

$$\llbracket \hat{\sigma} \rrbracket = 0, \quad \{\hat{\sigma}\} = \nabla u$$

$$\alpha^j(u, v) = 0$$

Consistency of NIPG Method (2)

Let u solve the model problem, by the integration by parts formula, we have for any $v \in H^2(\Pi_h)$ that

$$\int_{\Omega} \nabla_h u \cdot \nabla_h v dx = - \int_{\Omega} \Delta u v dx + \int_{\Gamma} \{\nabla_h u\} \cdot \llbracket v \rrbracket ds + \int_{\Gamma^0} \llbracket \nabla_h u \rrbracket \cdot \{v\} ds$$

With $\{u\} = u$, $\llbracket u \rrbracket = 0$, $\{\nabla_h u\} = \nabla_h u$, $\llbracket \nabla_h u \rrbracket = 0$, $-\Delta u = f$, we have

$$\begin{aligned} B_h(u, v) &:= \int_{\Omega} f v dx + \int_{\Gamma} (\llbracket \hat{u} \rrbracket \cdot \{\nabla_h v\} + (\nabla u - \{\hat{\sigma}\}) \cdot \llbracket v \rrbracket) ds \\ &+ \int_{\Gamma^0} (\{\hat{u} - u\} \llbracket \nabla_h v \rrbracket - \llbracket \hat{\sigma} \rrbracket \{v\}) ds + \alpha^j(u, v) \end{aligned} \quad (8)$$

If numerical fluxes are consistent, on Γ , $\llbracket \hat{u} \rrbracket = 0$, $\{\hat{u}\} = u$, $\llbracket \hat{\sigma} \rrbracket = 0$, $\{\hat{\sigma}\} = \nabla u$, we conclude that

$$B_h(u, v) = \int_{\Omega} f v dx \quad \forall v \in H^2(\Pi_h) \quad (9)$$

Adjoint Inconsistency of NIPG Methods (1)

Let ψ solve

$$\begin{aligned} -\Delta\psi &= g && \text{in } \Omega \\ \psi &= 0 && \text{on } \partial\Omega \end{aligned}$$

If $B_h(v, \psi) = \int_{\Omega} v g dx$ for all $v \in H^2(\Pi_h)$, we say that the primal form is adjoint consistent.

Since $\psi \in H^2(\Omega)$, $[[\psi]] = 0$, $\{\psi\} = \psi$, $[[\nabla\psi]] = 0$, $\{\nabla\psi\} = \nabla\psi$, by the integration by parts, we get

$$B_h(v, \psi) = \int_{\Omega} v g dx + \int_{\Gamma} [[\hat{u}(v)]] \cdot \nabla\psi ds - \int_{\Gamma^0} [[\hat{\sigma}(v, \sigma_h(v))]] \psi ds \quad \forall v \in H^2(\Pi_h) \quad (10)$$

Adjoint Inconsistency of NIPG Methods (2)

For the numerical fluxes of NIPG method, we calculate

$$\begin{aligned} [[\hat{u}]] &= [[\{v\} + n_K \cdot [v]]] \\ &= [[\{v\}]] + [[n_K \cdot [v]]] \\ &= n_1(n_1 \cdot (n_1 v_1 + n_2 v_2)) + n_2(n_2 \cdot (n_1 v_1 + n_2 v_2)) \\ &= n_1(v_1 - v_2) + n_2(v_2 - v_1) \\ &= 2(n_1 v_1 + n_2 v_2) = 2[[v]] \\ [[\hat{\sigma}]] &= [[\{\nabla_h v\}]] - [[\alpha_j([v])]] \\ &= 0 - 0 = 0 \end{aligned}$$

So, insert them into Equation (10)

$$B_h(v, \psi) = \int_{\Omega} v g dx + 2 \int_{\Gamma} [[v]] \cdot \nabla \psi ds$$

Penalty Term and DG Norm

The penalty term of NIPG method

$$\alpha^j(u, v) = \sum_{e \in \varepsilon_h} \int_e \eta_e h_e^{-1} [[u]] \cdot [[v]] ds, \quad (C_{e,0} \leq \eta_e \leq C_{e,1})$$

Take the norm of NIPG method in $V(h) = V_h + H^2(\Omega) \cap H_0^1(\Omega) \subset H^2(\Pi_h)$ as

$$\|v\|_h^2 = |v|_{1,h}^2 + \sum_{K \in \Pi_h} h_K^2 |v|_{2,K}^2 + |v|_*^2$$

where $|v|_{1,h}^2 = \sum_K |v|_{1,K}^2$, $|v|_*^2 = \alpha^j(v, v)$.

Boundedness of NIPG Method (1)

By noting if $u \in H^2(K)$ and e is an edge of K , we have trace inequality¹

$$\left\| \frac{\partial u}{\partial n} \right\|_{0,e}^2 \leq C(h_e^{-1}|u|_{1,K}^2 + h_e|u|_{2,K}^2), \quad \text{Then,}$$

$$\int_e \left| \frac{\partial u}{\partial n} q \right| ds \leq C(|u|_{1,K}^2 + h_e^2|u|_{2,K}^2)^{1/2} h_e^{-1/2} \|q\|_{0,e}, \quad \text{for every } q \in L^2(e),$$

$$\begin{aligned} \int_{\Gamma} \{\nabla_h u\} \cdot \llbracket v \rrbracket ds &= \sum_{e \in \varepsilon_h} \int_e \{\nabla_h u\} \cdot \llbracket v \rrbracket ds \\ &\leq C \left[\sum_K (|u|_{1,K}^2 + h_K^2|u|_{2,K}^2) \right]^{1/2} \left[\sup(1/\eta_e) \sum_{e \in \varepsilon_h} \eta_e h_e^{-1} \int_e \llbracket v \rrbracket^2 ds \right]^{1/2} \\ &\leq \sup(1/\eta_e) C \|u\|_h |v|_* \leq \sup(1/\eta_e) C \|u\|_h \|v\|_h \end{aligned}$$

¹D.N.Arnold, An interior penalty finite element method with discontinuous elements, SIAM J. Numer. Anal., 19(1982), pp. 742-760.

Boundedness of NIPG Method (2)

Similarly, we have $\langle [u], \{\nabla_h v\} \rangle = \int_{\Gamma} [u] \cdot \{\nabla_h v\} ds \leq C \|u\|_h \|v\|_h$
 Obviously, we have $(\nabla_h u, \nabla_h v) \leq C |u|_{1,h} |v|_{1,h} \leq C \|u\|_h \|v\|_h$,

$$\begin{aligned} \alpha^j(u, v) &= \sum_{e \in \varepsilon_h} \int_e \eta_e h_e^{-1} [u] \cdot [v] ds \leq \sum_{e \in \varepsilon_h} \left[\int_e \eta_e h_e^{-1} [u]^2 ds \right]^{1/2} \left[\int_e \eta_e h_e^{-1} [v]^2 ds \right]^{1/2} \\ &\leq \left[\sum_{e \in \varepsilon_h} \int_e \eta_e h_e^{-1} [u]^2 \right]^{1/2} \left[\sum_{e \in \varepsilon_h} \int_e \eta_e h_e^{-1} [v]^2 \right]^{1/2} \\ &= \alpha^j(u, u)^{1/2} \alpha^j(v, v)^{1/2} = |u|_* |v|_* \leq C \|u\|_h \|v\|_h \end{aligned}$$

Collecting all the terms which are bounded by the DG norm of the NIPG method, we get

$$\begin{aligned} B_h(u, v) &= (\nabla_h u, \nabla_h v) - \langle \{\nabla_h u\}, [v] \rangle + \langle [u], \{\nabla_h v\} \rangle + \alpha^j(u, v) \\ &\leq C_1 |u|_{1,h} |v|_{1,h} + C_2 |u|_* \|v\|_h + C_3 \|u\|_h |v|_* + C_4 |u|_* |v|_* \\ &\leq C \|u\|_h \|v\|_h \end{aligned}$$

Stability Analysis of NIPG Method (1)

Equivalence of DG and weak norm

$$|v|_{\#} = (|v|_{1,h}^2 + |v|_{*}^2)^{1/2} = (|v|_{1,h}^2 + \alpha^j(v, v))^{1/2}$$

$$\|v\|_h^2 = |v|_{1,h}^2 + \sum_{K \in \Pi_h} h_K^2 |v|_{2,K}^2 + |v|_{*}^2$$

By inverse inequality

$$\|\nabla v\|_0 \leq h^{-1} \|v\|_0$$

So

$$C_1 |v|_{\#}^2 \leq \|v\|_h^2 \leq C_2 |v|_{\#}^2$$

Stability Analysis of NIPG Method (2)

We show that the NIPG method satisfies the stability condition

$$B_h(v, v) \geq C_s |v|_{\#}^2 \quad \forall v \in V_h$$

We define the weak norm, the natural one for analyzing the stability of NIPG method

$$|v|_{\#} = (|v|_{1,h}^2 + |v|_{*}^2)^{1/2} = (|v|_{1,h}^2 + \alpha^j(v, v))^{1/2}$$

From the primal forms of the DG method, we have

$$\begin{aligned} B_h(v, v) &= (\nabla_h v, \nabla_h v) - \langle \{\nabla_h v\}, \llbracket v \rrbracket \rangle + \langle \llbracket v \rrbracket, \{\nabla_h v\} \rangle + \alpha^j(v, v) \\ &= (\nabla_h v, \nabla_h v) + \alpha^j(v, v) \\ &= \|\nabla_h v\|_{0,\Omega}^2 + \alpha^j(v, v) \\ &= |v|_{\#}^2 \geq C_s |v|_{\#}^2 \end{aligned}$$

Error Estimates (1)

A bound on the approximation error $\|u - u_I\|$, where $u_I \in V_h$, the usual continuous interpolant, then

$$\alpha^j(u - u_I, u - u_I) = \sum_{e \in \mathcal{E}_h} \int_e \eta_e h_e^{-2p-1} \llbracket u - u_I \rrbracket \cdot \llbracket u - u_I \rrbracket ds = 0$$

The norm of the NIPG method can be bounded by

$$\|u - u_I\|_h^2 = |u - u_I|_{1,h}^2 + \sum_{K \in \Pi_h} h_K^2 |u - u_I|_{2,K}^2 \leq C_a^2 h^{2p} |u|_{p+1,\Omega}^2$$

So

$$\|u - u_I\|_h \leq C_a h^p |u|_{p+1,\Omega}$$

By the stability of the NIPG method, we have

$$\begin{aligned} C_s \|u_I - u_h\|_h^2 &\leq B_h(u_I - u_h, u_I - u_h) \\ &= B_h(u_I - u, u_I - u_h) + B_h(u - u_h, u_I - u_h) \\ &= \{u_I - u_h \in V_h\} = B_h(u_I - u, u_I - u_h) \end{aligned}$$

Error Estimates (2)

Use the continuity of $u - u_I$, we have the estimate

$$\begin{aligned} C_s \|||u_I - u_h\|||_h^2 &= B_h(u_I - u, u_I - u_h) \\ &\leq C_b \|||u_I - u\|||_h \|||u_I - u_h\|||_h \\ &\leq C_b h^p \|||u_I - u_h\|||_h |u|_{p+1, \Omega} \end{aligned}$$

Thus by triangle inequality, we get

$$\begin{aligned} \|||u - u_h\|||_h &\leq \|||u - u_I\|||_h + \|||u_I - u_h\|||_h \\ &\leq C_a h^p |u|_{p+1, \Omega} + C_b h^p |u|_{p+1, \Omega} \\ &= Ch^p |u|_{p+1, \Omega} \end{aligned}$$

Error Estimates (3)

For the L^2 -error estimate of the NIPG method, let ψ is the solution of the adjoint problem

$$-\Delta\psi = u - u_h \quad \text{in } \Omega \quad \psi = 0 \quad \text{on } \partial\Omega$$

We then have

$$\|u - u_h\|_{0,\Omega}^2 = B_h(u - u_h, \phi) - 2 \int_{\Gamma} \{\nabla\phi\} \cdot \llbracket u - u_h \rrbracket ds =: T_1 + T_2$$

If ψ_I is the continuous interpolant of ψ in V_h , then $B_h(u, \psi_I) = (f, \psi_I)$, and

$$\begin{aligned} T_1 &= B_h(u - u_h, \psi) = B_h(u - u_h, \psi - \psi_I) \\ &\leq C \|\|u - u_h\|\|_h \|\|\psi - \psi_I\|\|_h \\ &\leq Ch \|\|u - u_h\|\|_h \|u - u_h\|_{0,\Omega} \end{aligned}$$

Error Estimates (4)

Use the definition of the penalty term and norm of the NIPG method, and apply the trace inequality, we get

$$\begin{aligned} \sum_{e \in \varepsilon_h} \int_e \{\nabla u\} \cdot \llbracket v \rrbracket ds &= \sum_{e \in \varepsilon_h} \int_e (h_e^{2p+1})^{1/2} \{\nabla u\} \cdot \llbracket v \rrbracket (h_e^{-2p-1})^{1/2} ds \\ &\leq C \|\llbracket v \rrbracket\|_h \left(\sum_{e \in \varepsilon_h} h_e^{2p+1} \int_e |\{\nabla u\} \cdot n_e|^2 ds \right)^{1/2} \leq Ch^p \|\llbracket v \rrbracket\|_h \|u\|_{2,h} \end{aligned}$$

Again use the elliptic regularity, we have

$$T_2 \leq Ch^p \|\llbracket u - u_h \rrbracket\|_h \|\psi\|_{2,\Omega} \leq Ch^p \|\llbracket u - u_h \rrbracket\|_h \|u - u_h\|_{0,\Omega}$$

Collect error estimates for T_1, T_2 , we obtain the desired optimal estimate

$$\|u - u_h\|_{0,\Omega} \leq Ch^{p+1} \|u\|_{p+1,\Omega}$$