

Lecture 4

31.10.16

Recall:

$A: D(A) \subset H_1 \rightarrow H_2$ linear, densely defined,
closed

$A^*: D(A^*) \subset H_2 \rightarrow H_1$ linear, densely defined,
closed

switch to
inj. operators

$$H_1 = N(A) \oplus_{H_1} \overline{R(A^*)}$$

$$H_2 = N(A^*) \oplus_{H_2} \overline{R(A)}$$

$$\Rightarrow N(A)^\perp = \overline{R(A^*)}$$



$$t: D(t) := D(A) \cap \overline{R(A^*)} \subset \overline{R(A^*)} \rightarrow \overline{R(A)}$$

$$t^*: D(t^*) := D(A^*) \cap \overline{R(A)} \subset \overline{R(A)} \rightarrow \overline{R(A^*)}$$

$\Rightarrow (A, A^*)$ & (t, t^*) are dual pairs

[i.e. $t^{**} = A$ resp. $t^{**} = A^*$]

$$D(A) = N(A) \oplus_{H_1} D(t) \Rightarrow R(A) = R(t)$$

$$D(A^*) = N(A^*) \oplus_{H_2} D(t^*) \Rightarrow R(A^*) = R(t^*)$$

cf. exercise 1, Problem 6 we have

$$D(t) \hookleftarrow H_1 \Leftrightarrow D(t^*) \hookleftarrow H_2$$



$R(A) = R(t)$ is closed

$\Leftrightarrow \exists C_A > 0 \quad \forall x \in D(t):$

$$\|x\|_{H_1} \leq C_A \|Ax\|_{H_2},$$

$$R(A^*) = R(A^*) \text{ is closed}$$

$$\Leftrightarrow \exists c_{A^*} > 0 \quad \forall y \in D(A^*):$$

$$\|y\|_{H_2} \leq c_{A^*} \|A^*y\|_{H_1}$$

We even have: $c_A = c_{A^*}$,
if we define:

$$\frac{1}{c_A} := \inf_{0 \neq x \in D(A)} \frac{\|Ax\|_{H_2}}{\|x\|_{H_1}}, \quad \frac{1}{c_{A^*}} := \inf_{0 \neq y \in D(A^*)} \frac{\|A^*y\|_{H_1}}{\|y\|_{H_2}}$$

Sequences:

Let $A_0: D(A_0) \subset H_0 \rightarrow H_1$, $A_1: D(A_1) \subset H_1 \rightarrow H_2$,
 t_0, t_1, t_0^*, t_1^* as above and assume

$$\boxed{t_1, t_0 = 0} \quad \text{sequence (complex) property}$$

(indeed here should be a "c", since
0 has a bigger domain of defin.)

$$\Rightarrow R(A_0) \subset N(A_1)$$

$$\stackrel{?}{\Rightarrow} R(A_1^*) \subset N(A_0^*)$$

(We can also put closure bars,
since closed operators have
closed kernels)

Theorem 5: (HH-decompositions)

$$* H_0 = N(A_0) \oplus_{H_0} \overline{R(A_0^*)}$$

$$* H_1 = \overline{N(A_1)} \oplus_{H_1} \overline{R(A_1^*)}$$

$$= \overline{R(A_0)} \oplus_{H_1} \overline{N(A_0^*)} \Rightarrow N(A_1) = \overline{R(A_0)} \oplus_{H_1} K_1$$

$$\Rightarrow H_1 = \overline{R(A_0)} \oplus_{H_1} K_1 \oplus_{H_1} \overline{R(A_1^*)}$$

If additionally $A_2 : D(A_2) \subset H_2 \rightarrow H_3$ linear, densely defined, closed with $A_2 A_1 = 0$, we have:

$$* H_2 = \frac{N(A_2)}{\cup} \oplus_{H_2} \overline{R(A_2^*)} \\ = \overline{R(A_1)} \oplus_{H_2} N(A_1^*) \Rightarrow N(A_2) = \overline{R(A_1)} \oplus_{H_2} K_2$$

$$\Rightarrow H_2 = \overline{R(A_1)} \oplus_{H_2} K_2 \oplus_{H_2} \overline{R(A_2^*)}$$

$$* H_3 = \overline{R(A_2)} \oplus_{H_3} N(A_2^*)$$

The spaces $K_1 := N(A_0^*) \cap N(A_1)$ and $K_2 := N(A_1^*) \cap N(A_2)$ are called "cohomology groups"

Proof:

Exercise 2, Problem 2

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Primal & dual sequences:

$$\begin{array}{ccccccc} D(A_0) & \xrightarrow{A_0} & D(A_1) & \xrightarrow{A_1} & D(A_2) & \xrightarrow{A_2} & H_3 \\ & & & & & & (\text{primal}) \\ H_0 & \xleftarrow{A_0^*} & D(A_0^*) & \xleftarrow{A_1^*} & D(A_1^*) & \xleftarrow{A_2^*} & D(A_2^*) \quad (\text{dual}) \end{array}$$

Definition:

We call a sequence

* complex: $\Leftrightarrow R(A_i) \subset N(A_{i+1})$

* closed: $\Leftrightarrow R(A_i)$ is closed

* exact: $\Leftrightarrow K_i = \{0\}$

(then: $\overline{R(A_i)} = N(A_{i+1})$)

Remark:

We have

- * primal sequence is a complex
 - \Leftrightarrow dual sequence is a complex.
- * primal complex is closed
 - \Leftrightarrow dual complex is closed.
(„closed range theorem“)
- * primal complex is exact
 - \Leftrightarrow dual complex is exact.
 $(N(t_2) = \overline{R(t_1)} \oplus_{H_2} U_2, N(t_1^*) = U_2 \oplus \overline{R(t_2^*)})$

If (t, t^*) is a dual pair, t linear, densely defined, closed, then

- * t^*t, tt^* are selfadjoint.
- * $\begin{pmatrix} 0 & t^* \\ t & 0 \end{pmatrix} : D(t) \times D(t^*) \subset H_1 \times H_2 \rightarrow H_1 \times H_2$
is selfadjoint.
- * $\begin{pmatrix} 0 & -t^* \\ t & 0 \end{pmatrix}$ is skew-selfadjoint.
 $\Rightarrow i \begin{pmatrix} 0 & -t^* \\ t & 0 \end{pmatrix}$ is selfadjoint.

Assume: $R(t_0) \subset R(t_1)$ are closed

$$\Rightarrow H_1 = R(t_0) \oplus_{H_1} U_1 \oplus_{H_1} R(t_1)^*$$
$$\hookrightarrow D(t_1) = R(t_0) \oplus_{H_1} U_1 \oplus_{H_1} D(t_1)$$

$$\Rightarrow D_\lambda := D(A_\lambda) \cap D(A_{\lambda}^*)$$

$$= D(A_{\lambda}^*) \oplus_{H_1} K_\lambda \oplus_{H_1} D(A_\lambda)$$

Lemma 6:

Let $R(t_0) \subset R(t_1)$ be closed. Then:

$$\forall x \in D_\lambda \cap K_\lambda^\perp : \|x\|_{H_1}^2 \leq C_{A_0}^2 \|A_0^* x\|_{H_0}^2 + C_{A_1}^2 \|A_1 x\|_{H_2}^2$$

Proof:

Let $y \in D_\lambda \cap K_\lambda^\perp$

$$\Rightarrow y = y_0 + y_1 \in D(A_{t_0}^*) \oplus_{H_1} D(A_{t_1})$$

$$\Rightarrow \|y\|_{H_1}^2 \leq \|y_0\|_{H_1}^2 + \|y_1\|_{H_1}^2$$

$$\begin{aligned} D(A_{t_0}^*) &\subset N(A_{t_1}) \\ D(A_{t_0}^*) &\subset N(A_{t_0}^*) \end{aligned}$$

$$\begin{aligned} &\leq C_{A_0}^2 \|A_0^* y_0\|_{H_0}^2 + C_{A_1}^2 \|A_1 y_1\|_{H_2}^2 \\ &= C_{A_0}^2 \|A_0^* y\|_{H_0}^2 + C_{A_1}^2 \|A_1 y\|_{H_2}^2 \end{aligned}$$

□

Apply "toolbox" to the Maxwell case:

Let $\mathcal{R} \subset \mathbb{R}^3$ open; $\epsilon, \mu: \mathcal{R} \rightarrow \mathbb{R}^{3 \times 3}$;

$\epsilon, \mu \in L^\infty(\mathcal{R})$, symmetric and uniformly positive definite.

$$\hat{A}_0 := \hat{\nabla}: \overset{\circ}{C} \infty \subset L^2 \rightarrow L^2_\epsilon, \hat{A}_0 u = \nabla u$$

$$\hat{A}_1 := \mu^{-1} \hat{\text{rot}}: \overset{\circ}{C} \infty \subset L^2_\epsilon \rightarrow L^2_\mu, \hat{A}_1 u = \mu^{-1} \text{rot} u$$

$$\hat{A}_2 := \hat{\text{div}} \mu: \mu^{-1} \overset{\circ}{C} \infty \subset L^2_\mu \rightarrow L^2, \hat{A}_2 u = \text{div}(\mu u)$$

~ all operators are linear, densely defined; but are they closable?

e.g. \hat{A}_1 closable:

$\forall (x_n)_n \subset D(\hat{A}_1) = \mathring{C}^\infty$ with

$$x_n \rightarrow 0 \quad \& \quad \hat{A}_1 x_n = \mu^{-1} \text{rot } x_n \rightarrow y$$

$\Rightarrow \forall \phi \in \mathring{C}^\infty:$

$$\begin{aligned} \langle y, \phi \rangle_{L^2_\mu} &= \langle y, \mu \phi \rangle_{L^2} \\ &= \lim_{n \rightarrow \infty} \langle \mu^{-1} \text{rot } x_n, \mu \phi \rangle_{L^2} \\ &= \lim_{n \rightarrow \infty} \langle \text{rot } x_n, \phi \rangle_{L^2} \\ &= \lim_{n \rightarrow \infty} \langle x_n, \text{rot } \phi \rangle_{L^2} = 0 \end{aligned}$$

$$\Rightarrow y = 0$$

$\Rightarrow \hat{A}_1$ is closable.

□

\rightsquigarrow closed operators: $D(\overline{\hat{A}_i}) = \overline{D(\hat{A}_i)}^{G(\hat{A}_i)}$

$$A_0 := \overline{\hat{A}_0} = \overset{\circ}{\nabla}: \overset{\circ}{H^1} \cap L^2 \rightarrow L^2_\varepsilon$$

$$A_1 := \overline{\hat{A}_1} = \mu^{-1} \overset{\circ}{\text{rot}}: \overset{\circ}{\mathcal{R}} \subset L^2_\varepsilon \rightarrow L^2_\mu$$

$$A_2 := \overline{\hat{A}_2} = \text{div } \mu: \mu^{-1} \overset{\circ}{\delta} \subset L^2_\mu \rightarrow L^2$$

(of course: linear, densely defined
and now closed)

\rightsquigarrow compute the adjoints:

$$* u \in D(\overset{\circ}{\nabla}^*) \wedge \overset{\circ}{\nabla}^* u = f$$

$$\Leftrightarrow u \in L^2_\varepsilon \wedge \exists f \in L^2 \quad \forall \varphi \in D(\overset{\circ}{\nabla}) = \overset{\circ}{H^1}:$$

$$\langle u, \overset{\circ}{\nabla} \varphi \rangle_{L^2_\varepsilon} = \langle f, \varphi \rangle_{L^2}$$

||

$$\langle \varepsilon u, \overset{\circ}{\nabla} \varphi \rangle_{L^2}$$

$$\Leftrightarrow \varepsilon u \in D \wedge f = -\operatorname{div} \varepsilon u$$

$$\Leftrightarrow u \in \varepsilon^{-1}D \wedge f = -\operatorname{div} \varepsilon u$$

$$\leadsto \boxed{A_0^* = -\operatorname{div} \varepsilon : \varepsilon^{-1}D \subset L_\varepsilon^2 \rightarrow L^2}$$

$$* u \in D(\mu^{-1}\overset{\circ}{\operatorname{rot}}) \wedge \mu^{-1}\overset{\circ}{\operatorname{rot}} u^* u = f$$

$$\Leftrightarrow u \in L_\mu^2 \wedge \exists f \in L_\varepsilon^2 \forall \varphi \in D(\mu^{-1}\overset{\circ}{\operatorname{rot}}) = \overset{\circ}{R}:$$

$$\langle u, \mu^{-1}\overset{\circ}{\operatorname{rot}} \varphi \rangle_{L_\mu^2} = \langle f, \varphi \rangle_{L_\varepsilon^2}$$

" " "

$$\langle u, \overset{\circ}{\operatorname{rot}} \varphi \rangle_{L^2} \quad \langle \varepsilon f, \varphi \rangle_{L^2}$$

$$\Leftrightarrow u \in R \wedge \overset{\circ}{\operatorname{rot}} u = \varepsilon f$$

$$\Leftrightarrow u \in R \wedge f = \varepsilon^{-1}\overset{\circ}{\operatorname{rot}} u$$

$$\leadsto \boxed{A_1^* = \varepsilon^{-1}\overset{\circ}{\operatorname{rot}} : R \subset L_\mu^2 \rightarrow L_\varepsilon^2}$$

$$* u \in D(\operatorname{div} \mu^*) \wedge \operatorname{div} \mu^* u = f$$

$$\Leftrightarrow u \in L^2 \wedge \exists f \in L_\mu^2 \forall \varphi \in D(\operatorname{div} \mu) = \overset{\circ}{\mu^{-1}D}:$$

$$\langle u, \underset{\in \overset{\circ}{D}}{\operatorname{div} \mu} \varphi \rangle_{L_\mu^2} = \langle f, \varphi \rangle_{L_\mu^2}$$

" "

$$\langle f, \mu \varphi \rangle_{L^2}$$

$$\Leftrightarrow u \in H^1 \wedge f = -\nabla u$$

$$\leadsto \boxed{A_2^* = -\nabla : H^1 \subset L^2 \rightarrow L_\mu^2}$$

Now apply Theorem 5:

$$* L^2 = N(\overset{\circ}{\nabla}) \oplus_{L^2} \overline{R(-\operatorname{div} \varepsilon)}$$

$$= \{0\} \oplus_{L^2} \overline{R(\operatorname{div})} = \overline{R(\operatorname{div})}$$

$$= \overline{\operatorname{div} D}$$

$$\begin{aligned}
* L^2 &= \overline{N(\mu^{-1} \text{rot})} \oplus_{L^2_\varepsilon} \overline{R(\varepsilon^{-1} \text{rot})} \\
&= \overline{\overset{\circ}{R}_0} \oplus_{L^2_\varepsilon} \varepsilon^{-1} \text{rot } R \\
&= \overline{R(\overset{\circ}{\nabla})} \oplus_{L^2_\varepsilon} N(-\text{div } \varepsilon) \\
&= \overline{\overset{\circ}{\nabla} H^1} \oplus_{L^2_\varepsilon} \varepsilon^{-1} D_0 \\
&= \overline{R(\overset{\circ}{\nabla})} \oplus_{L^2_\varepsilon} [N(-\text{div } \varepsilon) \cap N(\mu^{-1} \text{rot})] \oplus_{L^2_\varepsilon} \overline{R(\varepsilon^{-1} \text{rot})} \\
&\quad = \underline{N(\mu^{-1} \text{rot})} \\
&\quad = N(-\text{div } \varepsilon) \\
&= \overline{\overset{\circ}{\nabla} H^1} \oplus_{L^2_\varepsilon} (\overline{\overset{\circ}{R}_0} \cap \varepsilon^{-1} D_0) \oplus_{L^2_\varepsilon} \varepsilon^{-1} \text{rot } R \\
&\quad = \underline{\overset{\circ}{R}_0} \\
&\quad = \varepsilon^{-1} D_0
\end{aligned}$$

$$\begin{aligned}
* L^2_\mu &= \overline{N(\text{div } \mu)} \oplus_{L^2_\mu} \overline{R(\nabla)} \\
&= \overline{\mu^{-1} \overset{\circ}{D}_0} \oplus_{L^2_\mu} \overline{\nabla H^1} \\
&= \overline{R(\mu^{-1} \overset{\circ}{\text{rot}})} \oplus_{L^2_\mu} N(\varepsilon^{-1} \text{rot}) \\
&= \overline{\mu^{-1} \overset{\circ}{\text{rot}}} \oplus_{L^2_\mu} R_0 \\
&= \overline{R(\mu^{-1} \overset{\circ}{\text{rot}})} \oplus_{L^2_\mu} [N(\text{div } \mu) \cap N(\varepsilon^{-1} \text{rot})] \oplus_{L^2_\mu} \overline{R(\nabla)} \\
&\quad = \underline{N(\text{div } \mu)} \\
&\quad = N(\varepsilon^{-1} \text{rot}) \\
&= \overline{\mu^{-1} \overset{\circ}{\text{rot}}} \oplus_{L^2_\mu} (\overline{\mu^{-1} \overset{\circ}{D}_0} \cap R_0) \oplus_{L^2_\mu} \overline{\nabla H^1} \\
&\quad = \underline{\mu^{-1} \overset{\circ}{D}_0} \\
&\quad = R_0
\end{aligned}$$

$$\begin{aligned}
* L^2 &= \overline{R(\text{div } \mu)} \oplus_{L^2} N(\nabla) \\
&= \overline{\text{div } \overset{\circ}{D}} \oplus_{L^2} \overline{R}
\end{aligned}$$

We call:

- * $\mathcal{D}_D := \overline{\overset{\circ}{R}_0} \cap \varepsilon^{-1} D_0$ " Dirichlet Fields"
- * $\mathcal{D}_N := \overline{R_0} \cap \mu^{-1} \overset{\circ}{D}_0$ " Neumann Fields"

$A_0^* A_0 = \operatorname{div} \vec{\nabla}$, $A_1^* A_1 = \epsilon^{-1} \operatorname{rot} \vec{\mu}^{-1} \operatorname{rot}$ and
 $A_2^* A_2 = -\nabla \operatorname{div} \mu$ are selfadjoint.

skew-selfadjoint are for example:

$$\begin{pmatrix} 0 & -A_0^* \\ A_0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & \operatorname{div} \epsilon \\ \vec{\nabla} & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & -A_1^* \\ A_1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & \epsilon^{-1} \operatorname{rot} \\ \mu^{-1} \operatorname{rot} & 0 \end{pmatrix}$$

↳ Maxwell-operator

$$\begin{pmatrix} 0 & -A_2^* \\ A_2 & 0 \end{pmatrix} = \begin{pmatrix} 0 & \nabla \\ \operatorname{div} \mu & 0 \end{pmatrix}$$

lecture 4½

02.11.16

We have seen:

$$N(A_0) = \{0\} \Rightarrow \overline{R(A_0)} = L^2 = \overline{\operatorname{div} D}$$

$$N(A_2^*) = \mathbb{R} \Rightarrow \overline{R(A_2^*)} = \mathbb{R}^\perp = L_0^\perp = \overline{\operatorname{div} \vec{D}}$$

→ reduced operators (injective)

$$J_0: \overset{\circ}{H} \subset L^2 \rightarrow \overline{\nabla \overset{\circ}{H}} \subset \overset{\circ}{L^2}$$

$$J_1: \overset{\circ}{R} \cap \epsilon^{-1} \operatorname{rot} \overset{\circ}{R} \subset \epsilon^{-1} \operatorname{rot} \overset{\circ}{R} \rightarrow \mu^{-1} \overset{\circ}{\operatorname{rot} R}$$

$$J_2: \mu^{-1} \overset{\circ}{D} \cap \overline{\nabla H} \subset \overline{\nabla H} \rightarrow \overline{\operatorname{div} \overset{\circ}{D}} = \mathbb{R}^\perp$$

$$J_0^*: \epsilon^{-1} \overset{\circ}{D} \cap \overline{\nabla \overset{\circ}{H}} \subset \overline{\nabla \overset{\circ}{H}} \rightarrow L^2$$

$$J_1^*: R \cap \mu^{-1} \overset{\circ}{\operatorname{rot} R} \subset \mu^{-1} \overset{\circ}{\operatorname{rot} R} \rightarrow \epsilon^{-1} \overline{\operatorname{rot} R}$$

$$J_2^*: H \cap L_0 \subset L_0 \rightarrow \nabla H \quad (L_0 = L_1)$$

$$D(J_0^*) \cap D(J_1) \hookrightarrow H_2 \hookleftarrow D(J_0) \hookleftarrow H_0 \cap D(J_1) \hookleftarrow H_1 \cap$$

H_1 is finite dimensional

\rightsquigarrow Furthermore:

$$* D(t_0) \hookrightarrow H_0 \hookrightarrow D(t_0^*) \hookrightarrow H_1$$

$$* D(t_1) \hookrightarrow H_1 \hookrightarrow D(t_1^*) \hookrightarrow H_2$$

$$* D(t_0^*) \cap D(t_1) \hookrightarrow H_2$$

$\Rightarrow R(t_0)$ & $R(t_1)$ are closed

\Leftrightarrow Poincaré-type estimates

In more detail:

$$D(t_0) \hookrightarrow H_0$$

↑

$$D(t_0^*) \hookrightarrow H_1$$

$$\overset{\circ}{H} \hookrightarrow L^2 \text{ Rellich's scl. th.} \\ (\text{need: } \mathcal{R} \text{ bdd.})$$

↑

$$\underbrace{\varepsilon^{-1} D \cap \overline{\partial \overset{\circ}{H}}} \hookrightarrow L_\varepsilon^2 \\ = \varepsilon^{-1} D \cap \overset{\circ}{R}_0 \cap \mathcal{H}_0^\perp$$

$$D(t_1) \hookrightarrow H_1$$

↑

$$\underbrace{\overset{\circ}{R} \cap \varepsilon^{-1} \text{rot } \overset{\circ}{R}} \hookrightarrow L_\varepsilon^2 \\ = \overset{\circ}{R} \cap \varepsilon^{-1} D_0 \cap \mathcal{H}_0^\perp \quad (?)$$

↑

$$D(t_1^*) \hookrightarrow H_2$$

$$\underbrace{R \cap \mu^{-1} \text{rot } \overset{\circ}{R}} \hookrightarrow L_\mu^2 \\ = R \cap \mu^{-1} D_0 \cap \mathcal{H}_N^\perp$$

$$D(t_2) \hookrightarrow H_2$$

↑

$$\underbrace{\mu^{-1} \overset{\circ}{D} \cap \overline{\nabla \overset{\circ}{H}}} \hookrightarrow L_\mu^2 \\ = \mu^{-1} \overset{\circ}{D} \cap \overset{\circ}{R} \cap \mathcal{H}_N^\perp$$

↑

$$D(t_2^*) \hookrightarrow H_3$$

$$H^1 \cap L_\perp^2 = H_1^1 \hookrightarrow L^2$$

Rellich's scl. theorem
(need: \mathcal{R} bdd, segment
property)

[\mathcal{R} weak lipschitz]

$$H^1 \hookrightarrow L^2]$$

$D(\lambda_0^*) \cap D(\lambda_1) \hookrightarrow H_1 \quad \varepsilon^{-1} \mathcal{D} \cap \overset{\circ}{R} \hookrightarrow L_\varepsilon^2$
 Wenzl's selection theorem
 (need: \mathcal{R}_ε bounded, weak Lipschitz)



$D(\lambda_0) \hookrightarrow H_0 \quad \overset{\circ}{H} \hookrightarrow L^2$ (already: ✓)
 $\wedge D(\lambda_1) \hookrightarrow H_1 \quad \wedge \overset{\circ}{R} \cap \varepsilon^{-1} \text{rot } R \hookrightarrow L_\varepsilon^2$
 $\wedge U_1 = N(\lambda_1) \cap N(\lambda_0^*) \quad \wedge \overset{\circ}{R}_0 \cap \varepsilon^{-1} D_0 = \mathcal{H}_0$ is
 is finite dimens. finite dimensional.

$D(\lambda_1^*) \cap D(\lambda_2) \hookrightarrow H_2 \quad \mathcal{R} \cap \mu^{-1} \overset{\circ}{D} \hookrightarrow L_\mu^2$
 Wenzl's selection theorem
 (need: \mathcal{R}_μ bounded, weak Lipschitz)



$D(\lambda_1) \hookrightarrow H_1 \quad \overset{\circ}{R} \cap \varepsilon^{-1} \text{rot } R \hookrightarrow L_\varepsilon^2$ (?)
 $\wedge D(\lambda_2^*) \hookrightarrow H_3 \quad \wedge H_1^1 \hookrightarrow L^2$
 $\wedge U_2 = N(\lambda_2) \cap N(\lambda_1^*) \quad \wedge \mathcal{R}_0 \cap \mu^{-1} \overset{\circ}{D}_0 = \mathcal{H}_0$ is
 is finite dimens. finite dimensional.

Poincaré-type estimates:

$R(\lambda_i)$ closed $\Leftrightarrow \forall x \in D(\lambda_i): \|x\|_{H_i} \leq c_i \|t x\|_{H_{i+1}}$



$R(\lambda_i^*)$ closed $\Leftrightarrow \forall x \in D(\lambda_i^*): \|x\|_{H_{i+1}} \leq c_i \|t^* x\|_{H_i}$

→ apply to the Maxwell case:

* $R(A_0) = R(\overset{\circ}{\nabla}) = \overset{\circ}{\nabla} H^1$ closed (follows e.g. from Rellich's selection theorem)

$$\Leftrightarrow \forall x \in H^1: \|x\|_{L^2} \leq c_F \|\nabla x\|_{L^2_\mu}$$

$$\Leftrightarrow \forall u \in \varepsilon^{-1} D \cap \overset{\circ}{H}{}^1: \|u\|_{L^2_\mu} \leq c_F \|\operatorname{div} u\|_{L^2_\mu}$$

* $R(A_1) = \mu^{-1} \overset{\circ}{\operatorname{rot}} R$ is closed $\Leftrightarrow \overset{\circ}{\operatorname{rot}} R$ is closed (follows e.g. from Weich's selection theorem)

$$\begin{aligned} \Leftrightarrow \forall x \in R \cap \varepsilon^{-1} \overset{\circ}{\operatorname{rot}} R: \|x\|_{L^2_\mu} &\leq c_m \|\mu^{-1} \overset{\circ}{\operatorname{rot}} x\|_{L^2_\mu} \\ &= c_m \|\overset{\circ}{\operatorname{rot}} x\|_{L^2_{\mu^{-1}}} \end{aligned}$$

$$\begin{aligned} \Leftrightarrow \forall u \in R \cap \mu^{-1} \overset{\circ}{\operatorname{rot}} R: \|u\|_{L^2_\mu} &\leq c_m \|\overset{\circ}{\operatorname{rot}} u\|_{L^2_\varepsilon} \\ &= c_m \|\overset{\circ}{\operatorname{rot}} u\|_{L^2_{\varepsilon^{-1}}} \end{aligned}$$

* $R(A_2) = L^2_\perp$ is closed $\Leftrightarrow R(A_2^*)$ is closed

$\Rightarrow \nabla H^1$ is closed (follows e.g. from Rellich's selection theorem: $H^1 \hookrightarrow L^2$)

$$\Leftrightarrow \forall x \in \mu^{-1} \overset{\circ}{D} \cap \nabla H^1: \|x\|_{L^2_\mu} \leq c_p \|\operatorname{div} \mu x\|_{L^2_\mu}$$

$$\Leftrightarrow \forall u \in H^1_\perp: \|u\|_{L^2_\mu} \leq c_p \|\nabla u\|_{L^2_\mu}$$

Moreover:

$$* N(A_1) = K_1 \oplus_{L^2_\mu} R(A_0)$$

$$\Rightarrow R(A_0) = N(A_1) \cap K_1^\perp$$

$$\Rightarrow \overset{\circ}{\nabla} H^1 = R_0 \cap K_0^\perp$$

$$* N(A_0^*) = K_1 \oplus_{L^2_\mu} R(A_1^*)$$

$$\Rightarrow R(A_1^*) = N(A_0^*) \cap K_1^{\perp_{L_0^2}}$$

$$\Rightarrow \varepsilon^{-1} \text{rot } R = \varepsilon^{-1} D_0 \cap \mathcal{H}_D^{\perp_{L_0^2}}$$

* $N(A_2) = K_2 \oplus_{L_0^2} R(A_1)$

$$\Rightarrow R(A_1) = N(A_2) \cap K_2^{\perp_{L_0^2}}$$

$$\Rightarrow \mu^{-1} \overset{\circ}{\text{rot}} R = \mu^{-1} \overset{\circ}{D}_0 \cap \mathcal{H}_N^{\perp_{L_0^2}}$$

* $N(A_1^*) = K_2 \oplus_{L_0^2} R(A_1^*)$

$$\Rightarrow R(A_1^*) = N(A_1^*) \cap K_2^{\perp_{L_0^2}}$$

$$\Rightarrow \nabla H^1 = R_0 \cap \mathcal{H}_N^{\perp_{L_0^2}}$$

Lemma 7:

If \mathcal{R} bounded and convex, we have

$$C_m \leq C_p \leq \frac{\text{diam } \mathcal{R}}{\pi}$$